Title: Identifying aircraft from above

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# Abstract

We all know what an aircraft looks like, but does a computer? A seemingly simple task that can be carried out by individuals at age two, poses a complex problem to modern technology. Machine learning is a relatively new field with little research but already boasts claim to many applications such as driverless cars and face recognition systems. The development of object recognition is the center of many companies’ business models and objectives, making aircraft identification such an interesting topic to research.

Existing images of ground and aircraft are pre-processed using Histogram of Gradients to create feature descriptors. Feature descriptors describe the orientation of a gradient within an image subsection. Support Vector Machines are passed feature descriptors with labels for training. Once training is completed, the support vector machine accepts a test set and returns predictions. Large image search takes a large image and looks within a smaller area for aircraft. Search area parameters are provided by the user.

The results obtained from cross validation show an accuracy of 100% when identifying standalone aircraft. However, when searching for aircraft in larger images, accuracy drastically decreases to around 55% as some aircraft are overlooked. After optimization, the system used to identify aircraft can be applied to other identification problems with possible military and commercial uses.

# List of Symbols

|  |  |
| --- | --- |
| **Acronym** | **Meaning** |
| SVM | Support Vector Machine |
| PNG | Portable Network Graphics |
| px | Pixels |
| HOG | Histogram of Oriented Gradients |
| PIL | Python Image library |
| GUI | Graphical User Interface |
|  |  |
|  |  |
|  |  |
|  |  |

# Project Aims and Objectives

The original aims of this project have changed since the initial report. This was because of a change of approach to the given problem. The main objective is to allow a computer to differentiate between **aircraft** and **ground** images. This can be broken into several smaller objectives.

## Primary Objectives

1. To gather a set of aircraft and ground images to create a training and test set
2. To normalise the training and test set
3. Change the orientation of aircraft to ensure the face north
4. Resize the images so they can be pre-processed accurately
5. To pre-process the training set and label accordingly.
6. To Train an SVM with the Training set
7. To test the SVM with the test set
8. Further optimise the SVM by tuning decision boundaries
9. Cross-validate the training set
10. Display results of classification to user.

Assuming all primary objectives are completed successfully, additional objectives are to be attempted

## Additional goals

1. To attempt to recognise aircraft in a large image using user defined search criteria and show aircraft locations to user after search is completed.
2. To generate heat maps of large images to identify areas with a probability of containing aircaft
3. To attempt to recognise non-commercial aircraft such as private aircraft and helicopters.

# Methods

## Internal and External Libraries

During the project, I have used a variety of libraries to aid the completion of the projects aims and objectives. Writing code to support all functionality provided by product would be very difficult to to achieve in the tight timescale given.

The language I have chosen for this project is python as it has a large range of image processing libraries available and offers a wide range of features such as object orientation. Internal libraries come as standard with the python package whereas external libraries are developed by third parties. All third-party libraries used during this project are used in accordance to licensing laws and agreements laid out in there terms and conditions.

### OpenCV

The library used to read images from PNG format to NumPy arrays was OpenCV. OpenCV has tools for image manipulation and other image related functions. OpenCV was used to rotate images before training.

### Scikit-Learn

Scikit-Learn is a well-documented Machine learning library that offers a wide range of tools for machine learning, data mining and data analysis. Scikit-learn has developed a Support Vector Machine that can be easily utilised for aircraft identification. The SVM forms the basis of my product and classifies objects as it sees fit.

### Scikit-Image

Scikit-Image is a collection of image processing algorithms for the Python programming language. This library contains the HOG algorithm used in image pre-processing to allow the SVM to distinguish between objects in images.

### FPDF

FPDF is a library that allows interaction between Python and pdf files. This allows the results of classification to be saved to and viewed by the user.

### NumPy

NumPy is the fundamental package for scientific computing in Python [1]. It comes with a variety of features and functions such as mathematical, logical and shape manipulation. This makes it the perfect library to store images as arrays. Other libraries used during this project utlise NumPy often returning NumPy arrays after specific functions. During the training stages, images are rotated using NumPy’s rotate function.

### Matplotlib

Matplotlib is a 2D plotting library that produces publication quality figures. During this project, I used its features to display results of classification to the user and allow them to interact with them using the libraries GUI. This allows them to zoom in and move Images and plots around as they wished. The user can also choose to save the output if they wish for later viewing.

### Tkinter

Tkinter is the Python standard for GUI development. The library allows the development of complex windowed GUI’s. It allows the placement of buttons, labels, text boxes, images, radio buttons and drop-down menus. Tkinter also has GUI’s for functions such as file selection.

### PIL

PIL is python’s image library that adds support for opening and saving images in multiple image formats. The library contains functions to easily manipulate images and draw shapes/ text over them. The shape functions have been utilised in this project.

## Data set

For a computer to recognise an object, first you must teach it what the object looks like. There are many different learning techniques and methods to do this. The technique I chose to implement was supervised learning. To carry out supervised learning, a training set must be created. The training set must show an accurate representation of the object or the model will fail to understand what it is identifying.

### Images

The data set currently consists of 250 images of aircraft and 250 images of ground. Images were obtained from google earth by taking screenshots of airports and proceeding to crop aircraft and ground. Cropped images are then saved as individual images. Cropped images of aircraft have little empty space around them so that the SVM can focus primarily on the SVM. Examples of training images are shown in Figure 1.

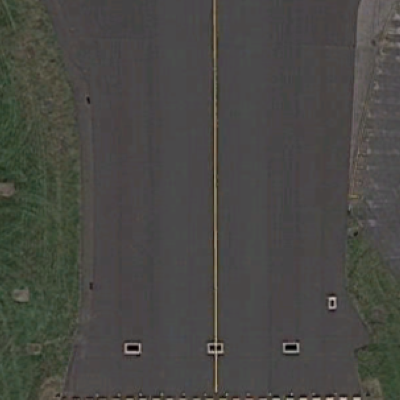


Figure 1: Image of ground (left) image of aircraft (right)

Originally, I ensured all images of aircraft were rotated so that the aircraft faced north. All images were also of the same dimensions (400x400 px) ensuring training was fair and balanced and are of the PNG format for simplicity.

However, after development of the image search classification method, it quickly became apparent that aircraft in real life can exist in many different sizes and rotations relative to image image search criteria. At present, the user defines the search area size and movement settings meaning the SVM may not always have a perfect view of an aircraft. The aircraft may appear off centre meaning the SVM will struggle to classify it. To overcome this problem, I needed to generate a realistic training set. To do this I gathered images of some aircraft at random rotations and of varying sizes therefore filling different amounts of the image. This gave the SVM a more realistic understanding of how an aircraft appears in real life.

To again simplify the realistic data set, I ensured each photo contained no more than one aircraft. If an image contained more than one aircraft, it would interpret an aircraft as an object of two or made of two aircraft combined. Figure 2 shows an example of this occurrence.



Figure 2: Image not included in data showing two aircraft

Images of aircraft with complicated surroundings such as complex jetways, terminals and vehicles in many cases were also disregarded. This is because it shifts the centre of attention of the SVM. The SVM will start to think an aircraft is an aircraft when it has an assortment of surrounding vehicles, buildings and jetways in proximity. The idea behind the

### Parsing

An image in computer science is regarded as an array of values. Each field contains a value which is displayed onscreen as a channels colour intensity. To train a machine learning model, the training set is provided as an array of image data. The image data created by reading images from the file system using the OpenCV library. The OpenCV function to read images, returns a NumPy array of raw image data. The image data is then added to a large array containing other training data. The process is repeated for every image in the training set until the training data is contained in a single array. Concurrent to this process, a separate label array is filled with 1’s and 0’s. 1 = Aircraft, 0 = Ground. This array tells the SVM which image belongs to which classifier.

To add an element of further realism, the method that generates the training set for the large image search, manipulates images at random to remove any element of bias that may be incurred by the default training set. This is done before training. Images are rotated randomly by intervals of 90 degrees and then pre-processed (see next section). They are then added to the large training array.

## Pre-Processing

Pre-processing takes an image and extracts key information about it. There are several pre-processing methods that are available and commonly used in machine learning. Pre-processing is used to reduce the load on the machine learning model and only supply it with relevant information. When images aren’t pre-processed, the machine learning model is often slow and inaccurate. This is because of the excess data provided to it. Image pre-processing creates a feature vector that describes an image. The feature vector is then provided to the machine learning model for training and evaluation.

### Histogram of oriented gradients

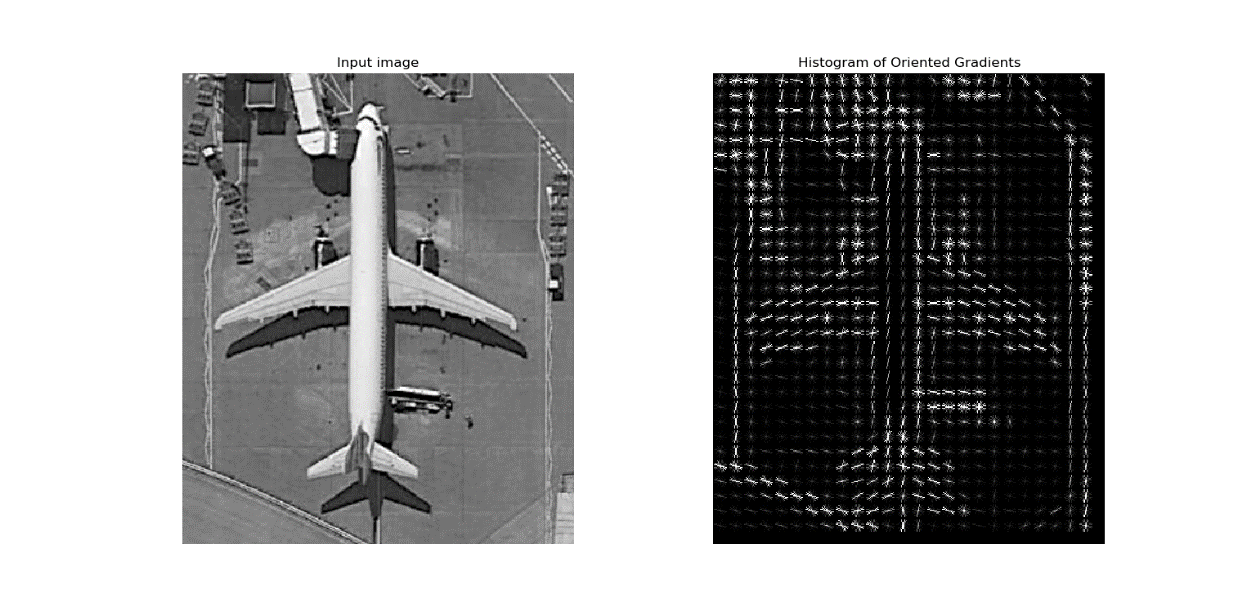
Histogram of oriented gradients is the current pre-processing method used in the parsing stage of the aircraft detection program. HOG counts the occurrences in gradient orientation in localized cells. The cells are normalised in blocks using contrast normalisation. A cell and blocks size can vary. Blocks can consist of any amount of cells. In this case, the blocks cells are normalised to ensure the results have low variance.

Contrast normalisation is a simple image enhancement technique that changes the range of image intensity values. Minimum and maximum values are supplied to a normalisation function which are applied to the image. This process is carried out to remove bias caused by illumination and shadowing in the given image.

After contrast normalisation is completed, the next step is to create a histogram for every cell in the image. Once the histogram is created, the orientation can be calculated. The direction of the gradient is added to a feature vector.

HOG was implemented in this program as it is widely used with SVM’s for object detection. Figure 3 shows a visualisation of the HOG algorithm on an aircraft from the training set.

Figure 3: Histogram of Oriented Gradients algorithm applied to a training image



The sizes of the cells are used in the HOG algorithm in the aircraft recognition program are 16x16px. The blocks consist of only one cell as this is the default value. If the SVM’s predictions were not accurate enough, the block sized can be increased if necessary to take make full use of contrast normalisation.

### Feature vector

A feature vector is a vector containing information describing an objects important details and characteristics. It can describe features and characteristics of a small area of an image or can describe an entire image. A feature can take many forms such as average density, centroid (centre of image where all medians intercept), pixel colour count, gradient magnitude and orientation.

The feature vector produced by HOG in the aircraft recognition system contains number of blocks per row, number of blocks per column, number of cells per row, number of cells per column and number of orientations and, orientation of every cell processed. Take an image with dimensions of 400x400px:

|  |  |  |
| --- | --- | --- |
| **Image size: 400x 400px (RGB)** | **Calculation** | **Length** |
| **Image length flattened** | (400x400)x3 | 480000 |
| **Feature Vector** | (400x400)/16 | 10000 |
| **Percentage difference** | (480000-10000)/480000\*100 | -97% (470000) |

By applying the HOG algorithm before training, we can not only reduce the amount of information passed to the SVM by roughly 97% but, increase the accuracy of the data passed to it. This plays a large part in computational complexity as the training and classification of a single image is 48 times faster. It is argued the application of HOG can add complexity to the system however, HOG will not increase the complexity by 48 times. Figure 4 shows the difference between an aircraft and ground feature vector.

A screenshot of a computer

Description automatically generated

Figure 4: Ground feature vector (Red), Aircraft feature vector (Blue)

## Machine learning

### Supervised learning

Supervised learning is the process of providing a machine learning model with labelled training data so it gains

### Support vector machines

What is an svm

### Kernel

### Hyper parameters and decision boundaries

### Tuning

Grid search

### Cross validation

What is cross validation and what scores did you get from different data sets?

### Data set

# Technical Achievement

## Normal standalone classification

## Large image search

# Project Planning

## Momentum

## Adapting to change

## Identifying and dealing with risks

## Achievement

## Performance

## What have I learnt?

# Conclusions

## Discussion

# References

[1] <https://docs.scipy.org/doc/numpy-1.13.0/user/whatisnumpy.html>

# Tables, Graphs, Figures and Equations

# Appendices

## Sustainability

## Legal

## Ethical

## Intellectual property